iWMC Integrated Servo Wheel Kinco Kinco

■ Terminal definition



| PIN | signal | PIN | signal |
|-----|--------|-----|--------|
| 1 | 24V | 10 | GND |
| 2 | LOCK+ | 11 | LOCK- |
| 3 | CANH | 12 | CANL |
| 4 | CANH | 13 | CANL |
| 5 | 485A | 14 | 485B |
| 6 | 485A | 15 | 485B |
| 7 | OUT1+ | 16 | сомо |
| 8 | COMI | 17 | DI1 |
| 9 | Empty | 18 | DI2 |

iWMC Integrated Servo Wheel Control Wiring Diagram

Digital signal input common | Digital signal input | Dil |

Wiring Diagram of Recommended Circuit for Forced Unlocking Brake



Note: The forced unlocking function needs to be used after the power supply of the servo wheel is cut off

Power port



| Pin number | Pin name | Pin function | |
|------------|----------|-----------------------------------|--|
| 3 | DC- | The input end of the power supply | |
| | | of the driver must be connected | |
| 1 | DC+ | Input voltage: 24~60VDC | |

Brake resistance port



| in number | Pin name | Pin function |
|-----------|----------|---------------------------|
| | RB+ | External braking resistor |
| | RB- | input terminal |

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iWMC Integrated Servo Wheel





- ☑ Design of dual power supply for driver
- ☑ Support external forced unlocking
- ☑ Standard CANopen communication protocol ☑ The reducer has low back seam and high precision

Superiority

Highly integrated: The four main components of the driver, motor, gearhead, and wheel are highly integrated, resulting in a compact structure that facilitates downsizing;

High mounting accuracy: Supported mounting, simple and convenient mounting method, high mounting accuracy, and high control accuracy;

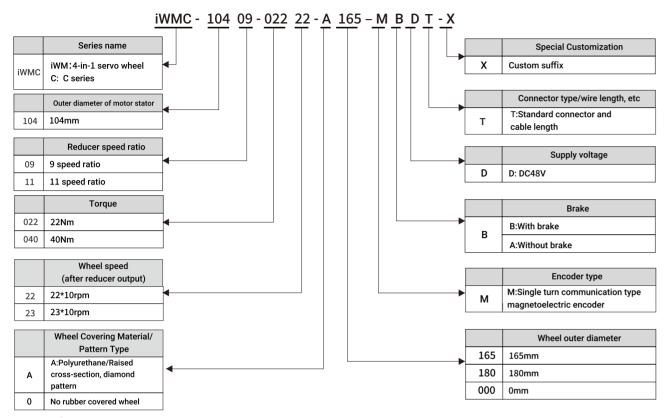
High reliability: The integrated module, with only external power supply and communication cables, is resistant to nickel-contacts and improves the stability and reliability of the entire system; Compatible design & seamless switching: the communication and usage modes of the servo wheel products are no different from those of the standard Kinco products, allowing seamless switching; Good maintainability: A single supplier for the integrated product facilitates the maintenance of the product at a later stage and reduces supply chain and after-sale costs.

Application Scenario

Power Servo Wheel Module for Mobile Machines with Loads up to 600 kg Power Servo Wheel Module for Mobile Machines with Loads up to 1 T

iWMC Integrated Servo Wheel

■ Naming convention



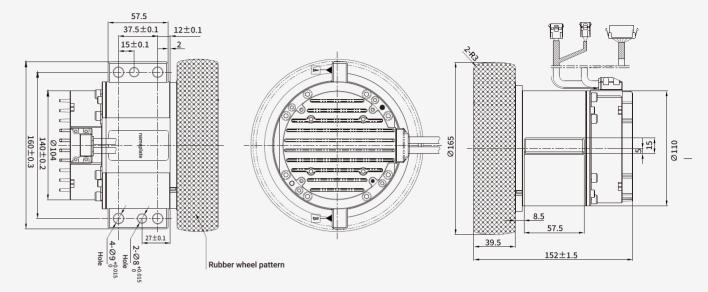
■ Product Parameters

| iWMC Integrate | ed Servo Wheel Model Number | iWMC10409-02222-A165-M■DT | iWMC10411-04023-A180-M■DT | | |
|---|-------------------------------------|---|---------------------------|--|--|
| Power | Power Supply | 24VDC~60VDC | | | |
| | Logic Supply | 24VDC | | | |
| Rated Linear Speed (m/s) | | 1.9 | 2.14 | | |
| Rated Torque Tn(Nm) | | 21 | 40 | | |
| Peak Torque Tn(Nm) | | 60 | 99 | | |
| Tire Diameter (mm) | | 165 | 180 | | |
| Tire Width(mm) | | 39.5 | 50 | | |
| Tire Material | | Polyurethane (optional) | | | |
| Tire Hardness Rating | | 85A | 90A | | |
| Energy Consumption Braking | | External braking resistor is required (depending on the operating conditions, mainly used for rapid starting and stopping) | | | |
| Energy Consumption Braking Voltage Absorption Point | | DC63V ± 2V(Default, settable) | | | |
| Overvoltage alarm point | | DC68V ± 2V | | | |
| Undervoltage alarm point | | DC18V ± 2V | | | |
| Input Specifications | | 2 digital inputs / Common COMI terminal / High level: 12.5-30VDC / Low level: 0-5VDC / Maximum frequency: 1KHz / Input impedance: 5ΚΩ. | | | |
| Output Specifications | | 1 digital output common COMO terminal / Maximum output current: 100mA | | | |
| Brake | | Built-in brake and control circuit | | | |
| Forced Unlock Interface | | 1-way forced unlock interface, only for use when there is no power input to the servo wheel | | | |
| RS485 Debug Port | | Maximum support for 115.2Kbps baud rate | | | |
| CAN BUS | | Maximum support for 1Mbps baud rate, CANopen protocol can be used to communicate with the controller | | | |
| Drive Current | Max. continuous output current (ms) | 16A | 26A | | |
| Drive Current | Peak Current (PEAK) | 100Ap(<2s) | 100Ap(<2s) | | |
| | Rated RPM nN(rpm) | 2000 | 2500 | | |
| Motor | Rated Torque Tn(Nm) | 2.4 | 4 | | |
| | Brake Holding Torque T(Nm) | 4 | | | |
| Noise | | <65dB | | | |
| Cooling Methods | | Natural cooling & Body-assisted cooling | | | |
| Operating | Operating Temperature | 0~40°C | | | |
| | Storage Temperature | -20°C~60°C | | | |
| | Humidity (non-condensing) | 90%RH below | | | |
| Environment | Protection Level | IP54 | | | |
| Limionnenc | Altitude | The rated working altitude is up to 1000m above sea level. For working altitudes above 1000m, a reduction of 1.5% is required for every 100 meters of rise in altitude, with a maximum working altitude of 2000 meters above sea level. | | | |
| | Atmospheric Pressure | 86kpa~106kpa | | | |
| | | a coulea moulea | | | |

Note: ■ = A : Without brake B : With brake

iWMC Integrated Servo Wheel

■ iWMC10409-02222-A165-M■DT



■ iWMC10411-04023-A180-M■DT

